

L Number	Hits	Search.Text	DB	Time stamp
1	2	5584019.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 09:27
2	44	transputer.ti.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 09:27
13	1	5584019.pn. and (cod\$3 or success\$5 or execut\$5 or authoriz\$5 or permit\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 12:56
14	2	5584019.pn. and (output\$4 or sequenc\$3 or efficien\$3 or optim\$7)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 12:43
15	0	5584019.pn. and (control\$4 near2 means)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 12:57
16	0	5584019.pn. and (control\$4 near2 mean)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 12:57
17	0	5584019.pn. and (control\$4 adj mean)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 12:57
18	0	5584019.pn. and (mean near2 control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 12:57
19	2	5584019.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 12:57
20	2	5584019.pn. and (control\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:08
21	1	5584019.pn. and (RT)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:34
22	1	5742823.pn. and (plac\$5 or position\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:36

23	1	6247064.pn. and (plac\$5 or position\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:37
24	48473	(placement or position\$3) with (robot or machin\$3 or equipment or apparatus or turret) with automatic\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:38
25	8032	((placement or position\$3) with (robot or machin\$3 or equipment or apparatus or turret) with automatic\$4).clm.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:39
26	3671	((placement or position\$3) with (robot or machin\$3 or equipment or apparatus or turret) with automatic\$4 with (operat\$3 or control\$4)).clm.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:44
27	9740	700/2,4,11,12,23-26,97,99-103.ccls. or 718/1,100-108.ccls. or 709/201,208.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:40
28	2	((placement or position\$3) with (robot or machin\$3 or equipment or apparatus or turret) with automatic\$4 with (operat\$3 or control\$4)).clm.) and (700/2,4,11,12,23-26,97,99-103.ccls. or 718/1,100-108.ccls. or 709/201,208.ccls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:40
29	4	("5463543" "5473531" "5623680" "5640319").PN.	USPAT	2004/03/08 13:41
30	194	((placement or position\$3) with (robot or machin\$3 or equipment or apparatus or turret) with automatic\$4 with (operat\$3 or control\$4)).clm.) and (700/\$.ccls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:43
32	20	((placement or position\$3) with (robot or machin\$3 or equipment or apparatus or turret) with automatic\$4 with (operat\$3 or control\$4)).clm. and (plural\$4 adj (process\$3 or operations)).clm.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 14:06
31	3	((placement or position\$3) with (robot or machin\$3 or equipment or apparatus or turret) with automatic\$4 with (operat\$3 or control\$4)).clm. and (plural\$4 adj processes).clm.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 13:45
34	17	((placement or position\$3) with (robot or machin\$3 or equipment or apparatus or turret) with automatic\$4 with (operat\$3 or control\$4)).clm. and (plural\$4 adj (process\$3 or operations)).clm.) not (((placement or position\$3) with (robot or machin\$3 or equipment or apparatus or turret) with automatic\$4 with (operat\$3 or control\$4)).clm. and (plural\$4 adj processes).clm.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 14:03
35	41	((placement or position\$3) near2 (robot or machin\$3 or equipment or apparatus or turret) near2 automatic\$4 near2 (operat\$3 or control\$4)).clm.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 14:28
36	59	((placement or position\$3) near3 (robot or machin\$3 or equipment or apparatus or turret) near3 automatic\$3 near3 (operat\$3 or control\$4)).clm.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 14:32

37	34	(((placement or position\$3) near3 (robot or machin\$3 or equipment or apparatus or turret) near3 automatic\$3 near3 (operat\$3 or control\$4)).clm.) not (((placement or position\$3) near2 (robot or machin\$3 or equipment or apparatus or turret) near2 automatic\$4 near2 (operat\$3 or control\$4)).clm.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 14:29
38	394	(automatic\$4 adj (placement or position\$3) adj (system or machine or turret))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 14:32
39	30	(automatic\$4 adj (placement or position\$3) adj (system or machine or turret)).clm.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 14:55
40	1	(automatic\$4 adj (placement or position\$3) adj (system or machine or turret)).clm. and (printer or (copy\$3 adj machine) or xerox)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 14:37
41	10	((automatic\$4 adj (placement or position\$3)) with (copier or (copy\$3 adj machine) or printer)).clm.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/03/08 14:57